

IN THE CLAIMS:

The text of all pending claims, (including withdrawn claims) is set forth below. Cancelled and not entered claims are indicated with claim number and status only. The claims as listed below show added text with underlining and deleted text with ~~strikethrough~~. The status of each claim is indicated with one of (original), (currently amended), (cancelled), (withdrawn), (new), (previously presented), or (not entered).

Please AMEND claims 1 and 5-7, and ADD new claims 9-16, as follows:

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1. (CURRENTLY AMENDED) A coordinate detection device, comprising:
an input unit ~~which has~~, having a surface thereof, to which a coordinate value is input by an input means;
a calculation unit ~~which calculates~~ calculating a difference between ~~previous and current~~ coordinate values of previous and current input operations by said input unit, the coordinate values being successive over detachment of the input means from the surface of said input unit; and
a setting unit ~~which sets~~ setting, in said calculation unit, a coordinate value ~~input last before at a time when~~ the input means is detached from the surface of said input unit as the ~~previous coordinate value to a coordinate value input first after the input means is detached from the surface of said input unit~~ of the previous input operation.
 2. (ORIGINAL) The coordinate detection unit as claimed in claim 1, further comprising:
a determination unit which determines an operation mode of said input unit; and
a control unit which enables or disables said setting unit based on a determination result of said determination unit.
 3. (ORIGINAL) The coordinate detection device as claimed in claim 2, wherein said determination unit determines the operation mode of said input unit based on a contact area formed by a contact of the input means with the surface of said input unit.
 4. (ORIGINAL) The coordinate detection device as claimed in claim 2, wherein said determination unit determines the operation mode of said input unit based on a time during which the input means is detached from the surface of said input unit.
 5. (CURRENTLY AMENDED) A method of detecting coordinates, comprising the steps of:
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(a) inputting a coordinate value to a surface of an input unit, by an input means;
(b) calculating a difference between ~~previous and current~~ coordinate values of previous and current input by said ~~step (a) inputting~~, the coordinate values being successive over detachment of the input means from the surface of said input unit; and
(c) setting, in said ~~step (b) calculating~~, a coordinate value input last before at a time when the input means is detached from the surface of the input unit as the previous coordinate value to a coordinate value input first after the input means is detached from the surface of the input unit of the previous input operation.

6. (CURRENTLY AMENDED) The method as claimed in claim 5, further comprising ~~the steps of~~:

(d) determining an operation mode of said ~~step (a) inputting~~; and
(e) enabling or disabling said ~~step (c) setting~~ based on a determination result of said ~~step (d) determining~~.

7. (CURRENTLY AMENDED) The method as claimed in claim 6, wherein said ~~step (d) determining~~ determines the operation mode of said ~~step (a) inputting~~ based on a contact area formed by a contact of the input means with the surface of the input unit.

8. (CURRENTLY AMENDED) The method as claimed in claim 6, wherein said ~~step (d) determining~~ determines the operation mode of said ~~step (a) inputting~~ based on a time during which the input means is detached from the surface of the input unit.

9. (NEW) A coordinate detection device, comprising:
an input unit, having a surface thereof, to which a coordinate value is input;
a calculation unit calculating a difference between a coordinate value of a first input operation and a coordinate value of a second input operation; and
a setting unit setting, in said calculation unit, the coordinate value of the first input operation as the final coordinate value input of the first input operation.

10. (NEW) The coordinate detection unit according to claim 9, further comprising:
a determination unit determining an operation mode of said input unit; and
a control unit enabling or disabling said setting unit based on a determination result of said determination unit.

11. (NEW) The coordinate detection device according to claim 10, wherein said determination unit determines the operation mode of said input unit based on an area of contact area between an input part and the surface of said input unit.
12. (NEW) The coordinate detection device according to claim 10, wherein said determination unit determines the operation mode of said input unit based on a time between the end of the first input operation and the beginning of the second input operation.
13. (NEW) A method of detecting coordinates, comprising:
inputting at least one coordinate value to a surface of an input unit;
setting a coordinate value of a first inputting as the final coordinate value input of the first inputting if a second inputting has not occurred for a predetermined time; and
calculating a difference between the set coordinate value of the first inputting and an initial coordinate value of the second inputting.
14. (NEW) The method according to claim 13, further comprising:
determining an operation mode of inputting; and
enabling or disabling said setting based on a result of said determining.
15. (NEW) The method according to claim 14, the determining based on an area of contact of the inputting.
16. (NEW) The method according to claim 14, the determining based on a time between the first inputting and the second inputting.

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